

### **QA-OMNI**











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### OA-OMNI





#### **SAFETY WARNINGS AND CAUTIONS**

The following warnings and cautions must be observed to ensure personal safety and prevent damage.



Death or serious injury may result from failure to heed this warning.



It is necessary to comply with national regulations when installing and picking materials for power lines.



Material damage or serious personal injury may result from failure to heed this warning.



Repairs and modifications must be carried out only by the manufacturer. It is forbidden to open the case and make any changes to the device. Tampering with the device will invalidate the warranty.



The manufacturer **declines all responsibility** for electrical safety in the event of improper use of the equipment.



It is essential to read the entire contents of this manual before carrying out any work.

Installation and commissioning must be carried out by qualified personnel only.



Before commissioning, make sure that:

- the maximum values for all connections are not exceeded; refer to the product data sheet;
- the connection cables are not damaged or live during wiring;
- the direction of current flow and phase rotation are correct.

During installation, ensure that a switch or circuit-breaker is near the product and easily accessible.

The unit must be uninstalled if safe operation can no longer be guaranteed (e.g. visible damage). Disconnect all connections in this case. The unit should be returned to the manufacturer or to an authorised service centre for repair.



WARNING: High-intensity magnetic fields may alter the values measured by the transformer. Avoid installation near: permanent magnets, electromagnets, or iron masses. If irregularities are detected, reposition or move the unit to a more suitable location.



Failure to observe the warnings may result in damage to the equipment or failure to operate as intended.



Please note that the information on the nameplate must be observed.



The product described in this document may only be used for the specified application. The maximum performance data and environmental conditions specified in the product data sheet must be observed. Proper transport and storage, as well as professional assembly, installation, handling and maintenance are required for the correct and safe operation of the device.

Use under ambient conditions other than those specified, application of signals or voltages other than those specified, may cause significant deviations from the specified measurement tolerances, which may be irreversible.



Although the contents of this document have been checked for accuracy, it may contain errors or inconsistencies and we cannot guarantee its completeness or accuracy.



This document is subject to periodic revision and updating. QEED reserves the right to make changes to the product and/ or its technical documentation at any time in the interests of continuous quality improvement. Always consult the latest version of the documentation available on the website:

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If you find any errors or missing information in this document, please notify us by e-mail to:

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Disposal of waste electrical and electronic equipment (applicable in the European Union and other countries with separate collection). The symbol on the product or its packaging indicates that the product should not be treated as household waste. Instead, it will be handed over to an authorised collection point for the recycling of electrical and electronic waste. Ensuring that the product is disposed of properly will prevent potential negative effects on the environment and human health, which could otherwise be caused by inappropriate waste management of the product. Recycling materials helps to conserve natural resources. For further information, please contact your local authority, waste disposal service or the retailer from whom you purchased the product.



#### **PRODUCT OVERVIEW**

The QA-OMNI is a universal signal converter configurable via USB and RS485 that can read analogue current, voltage, potentiometer, temperature (RTD and thermocouple) and digital frequency inputs.

It has a software configurable 0...20mA or 0...10V output and an alarm contact.

It can run from both AC or DC power.

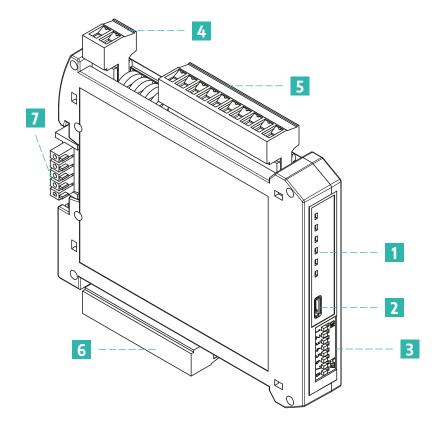
It has full galvanic isolation between power supply, serial and USB interface and inputs and outputs.

Power/error/communication/output status LEDs are on the front of the case.

RS485 serial interface for communication with Modbus RTU protocol, either from the Q-WIZARD configuration tool (download at link), or with third party Modbus masters by acting on register map registers.

Data acquisition via USB with integrated real-time clock data storage, with cable or OTG pendrive only.

Ready for DIN rail mounting with T-BUS terminal (optional) for fast connection with hot insertion/removal option.



- 1 Status LEDs
- 2 MicroUSB Port
- 3 Settings DIP switch
- 4 Power supply terminals
- 5 Input terminals
- 7 Output terminals
- 8 T-BUS terminal for both power supply and Modbus RTU communication (optional)





#### **Inputs**

- Voltage: configurable\* 0-10V, 100kΩ input impedance, 1mV resolution
- **Current**: configurable\* up to 20mA, 20Ω input impedance, 2μA MAX resolution
- · Temperature:
  - **RTD**: Pt100, Pt500, Pt1000, Ni100 (type 385). 2,3 or 4-wire measurement, automatic wire break detection, up to  $4000\Omega$  or  $4000\Omega$
  - **Thermocouple**: J, K, R, S, T, B, E, N; automatic thermocouple break detection
- Potentiometer: 1000Ω to 10kΩ
- **Resistance**:  $400\Omega$  or  $4k\Omega$  measurement. 2,3 or 4-wire measurement
- Frequency: 0.001Hz to 9.99kHz with (electro-)mechanical contacts, NPN 2 and 3-wire, PNP 3-wire with 24Vpc power supply, NAMUR, photoelectric, Hall sensor, variable reluctance, 24VDC pulse, TTL

#### **Outputs**

- Voltage: configurable\* 0-10V, minimum load resistance 2kΩ
- Current: configurable\* 0...20mA, maximum load resistance 600Ω
- Alarm contact: 5A / 230VAc relay, configurable via Q-WIZARD software

#### **Communication interface**

- RS485 Modbus RTU: connection to RS485 serial bus on module base via adapter (T-BUS optional) or terminals. Front dip-switch for manual setting of address and baud rate
- USB for configuration
- \* Using the configuration software, it is possible to scale the inputs and outputs as required, selecting the input measurement interval (BEGIN SCALE INPUT and END SCALE INPUT parameters in the configuration software) to which the analogue output signal is assigned (BEGIN SCALE OUTPUT and END SCALE OUTPUT parameters in the configuration software).

If manual control via Modbus RTU is selected from the interface, it is possible to manage the module as if it were an AO (Analogue Output) or a DO (Digital Output), thus freeing the analogue and digital output from the selected input. The analogue output is managed via the RS485 Modbus RTU (see register map).

#### **Reports and alerts**

The device notifies the user of the following faults via the LED interface:

- Input signal below threshold
- Input signal above threshold
- HW error in the measurement chain
- LOG problem of the real time clock storing the date and time
- RTC problem during data acquisition (no memory on USB stick, USB stick not recognised)
- EEPROM problem on the configuration microprocessor (module out of order, configuration lost)

These anomalies can also be associated with the analogue and/or digital output (even simultaneously) in the form of alarms.

An additional alarm can also be associated with the analogue and/or digital output on the input measurement reported at the output; depending on the configuration software settings, this alarm can be triggered when the measurement is above/below a set threshold or between/beyond 2 set thresholds.

**PLEASE NOTE**: in the event of an alarm, the output is set to 21mA or 10.5V depending on the analogue output mode setting (current or voltage) selected via the configuration software.

#### **Data logging**

It is possible to activate the LOG function for data acquisition on a USB flash drive from the configuration software's dedicated menu.

The extension of the log file can be of the following types: .xls, .xlsx, .csv, .txt, .dat, .log and can be changed by simply changing the extension to the file name in the configuration tool's save box. The default extension is text.

The minimum sampling time is 1 second and the maximum is approximately 18 hours.



### **TECHNICAL SPECIFICATIONS**

### **Electrical characteristics**

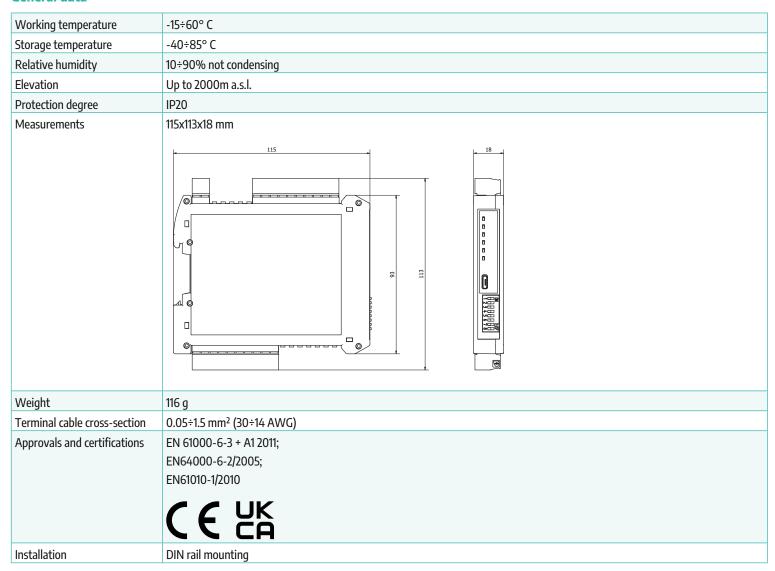
Power supply		10÷40 Vpc or 20÷28 Vac @50/60Hz		
Current consumption		250mA max		
Isolation		1.5kV galvanic isolation between inputs, analogue outputs, RS485 and USB interfaces and power supply		
Precision class		0.1% F.S.		
		* for thermocouples ±1°C for cold junction		
Temperature coefficient		<100ppm/°C		
Retransmitted output		Configurable analogue in passive and active current (max. voltage 24V)		
·		Power supply for passive sensors: 13Vpc, 30mA max		
Resolution		16 bits (15 bits + sign for thermocouples)		
Input		<b>Voltage</b> : configurable* 0-10V, 100kΩ input impedance, 1mV resolution		
		<b>Current</b> : configurable* up to 20mA, 20Ω input impedance, 2μA MAX resolution		
		Temperature:		
		• RTD (type 385): Pt100 (-200÷600°C), Pt500 (-100÷600°C), Pt1000 (-100÷600°C), Ni100 (-60÷180°C)		
	Analog *	• TC type: J (-200÷2000°C), K (-260÷1360°C), R(-40÷1760°C), S(-40÷1760°C), T(-260÷400°C),		
		B(-40÷1820°C), E(-260÷1000°C), N(-260÷1280°C)		
		Input range: -10mV to +70mV		
		Potentiometer: resistive value from 1k $\Omega$ to 10k $\Omega$		
		Resistance: $400\Omega$ or $4k\Omega$ measurement. 2,3 or 4-wire measurement		
Digital		Frequency: 0.001Hz to 9.99kHz with (electro-)mechanical contacts, NPN 2 and 3-wire, PNP 3-wire with 24Vpc power supply, NAMUR, photoelectric, Hall sensor, variable reluctance, 24Vpc pulse, TTL		
* Sampling time		100ms, with configurable averaged input value up to a maximum of 32 samples		
Output		Analog configurable in:		
·		<ul> <li>Current: configurable* 020mA, maximum load resistance 600Ω</li> </ul>		
		- Current: configurable* 020mA, maximum load resistance $600\Omega$		
		Digital (relay SPDT 250VAC, 5A MAX)		
Communication interface		RS485 Modbus RTU		
		microUSB port		
Visual interface		Status LEDs		

### **Communication characteristics**

Protocol	Modbus RTU	
Baudrate	1200÷115200 bps (default 9600)	
Addresses	1÷247 (default 1)	
Data format	1 start bit, 8-bit data, NO/ODD/EVEN parity (default NO parity)	
Response delay	1÷1000ms	
Connection	Via removable terminal, T-BUS or microUSB	



### **General data**



### **Order codes**

Product	QA-OMNI
Product without logo	QA-OMNI-T-NL
T-BUS	QA-TBUS-22



### **CONNECTION AND INSTALLATION**

For the connection of several instruments with reduced wiring, the unit is designed for DIN rail mounting, with or without T-BUS connector. The functionality of the terminals is described below:

16  AC MAX 2,5 VA 10-40 Vdc 17  AC 20-28 Vac	Device power supply  Please note: Wiring must be protected against short circuits and/or accidental faults
$ \begin{array}{c c} 1 & \bigcirc \\ 2 & \bigcirc \\ 3 & \bigcirc \\ 4 & \bigcirc \\ 5 & \bigcirc \\ 6 & \bigcirc \\ \end{array} $	Analogue input connection:  - 2-wire RTD sensor: terminals 3 and 6  - 3-wire RTD sensor: terminals 3, 4 and 6  - 4-wire RTD sensor: terminals 3 and 4  - Potentiometer: terminals 3, 4 and 6  - Active current input: terminals 2 (positive) and 3  - Passive current input: terminals 2 (positive) and 10  - Voltage input: terminals 1 (positive) and 3
S REED NAMUR - S REED	Digital input connections:  - (electro-) mechanical contact, 2-wire NPN and NAMUR: terminals 7 and 9  - 3-wire NPN with 12Vpc power supply: terminals 7, 9 and 10  - Photoelectric input, Hall sensor and 3-wire PNP with 24Vpc power supply: terminals 7, 8 and 10  - 24Vpc and TTL pulses: terminals 7 and 9  - Variable reluctance: terminals 8 and 9
MAX 24V	Analog output connection:  - Voltage: terminals 31 and 29 (positive)  - Active current: terminals 29 (positive) and 30  - Passive current: terminals 30 (positive) and 31  Sensor power supply from analogue output: 24Vpc, 30mA maximum
RELAY MAX 250Vac COM ② 26 MAX 5A NC ② 27	Digital output SPDT 5A / 250V <sub>AC</sub> changeover relay 25 normally open (NO) 27 normally closed (NC) The default setting is NO Relay 250V <sub>AC</sub> MAX and 5A MAX





ModBus GND	RS485 Modbus RTU connection: terminals 32 (GND), 33 (B-), 34 (A+)
O AC O AC O GND O B-	T-BUS connection (requires optional T-BUS accessory): the T-BUS accessory can be fitted to the module base to provide both power supply and serial communication (see figure below). The number of modules supported by the bus depends on the power supply used (please check the power consumption of the modules)

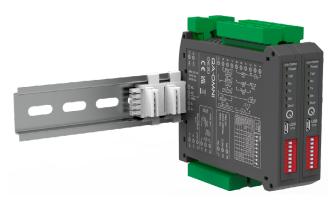


Figure 1: DIN-rail installation with T-BUS

#### **RS485 bus termination**

To avoid unbalances on the transmission bus, it is advisable to insert a termination resistor at the beginning of the RS-485 bus (typically on the USB-RS485 adapter) and at the end (typically on the last slave - which can also be activated by dip-switch). It is advisable to use  $120\Omega$  resistors with 1% tolerance, which corresponds to the typical impedance of RS485 cables.

The following images are for illustrative purposes only:

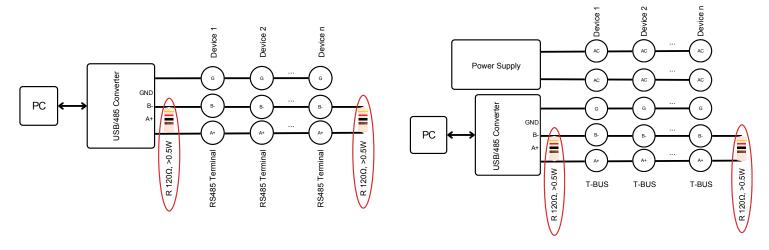


Figure 2: RS485 dynamic bus termination



#### **STATUS LEDS**

Function	Status	Meaning	
Power (green)	ON	Powered device	
Fail (yellow)	ON	Presence of one or more module anomalies/errors (configurable via Q-WIZARD o or via dedicated registers - see page 15)	
RX (red)	Flashing	The system is receiving data on the RS485	
TX (red)	Flashing	The system is transmitting data on the RS485	
Din (green)	ON	Active digital input	
Dout (green)	ON	Active digital output	

#### **DATA LOGGING - DATA ACQUISITION**

The QA-OMNI is able to provide a series of information regarding the module operation, alarm status, input type, output type, measured data reading, totalization, period and frequency measurement and module output value on a local USB PENDRIVE type memory (USB KEY) connected to the module via the microUSB port. The module is equipped with an RTC Real Time Clock powered by a backup battery, allowing the recording of data with year-month-day-hour-min-sec.

Log file example of a J thermocouple, 0-10V output, 1 sample per second:

Serial	Data (yyyy-mm-dd) & Time	Status	Analog Input	Totalizer	Period [us]	Frequency [Hz]	Analog Output	Input type	Output type
12345678	2014/03/12-14-23-25	0	27.36	0	123456	0,000008	359	21	0
12345678	2014/03/12-14-23-26	0	27.36	0	123457	0,000008	359	21	0
12345678	2014/03/12-14-23-27	0	27.36	0	123458	0,000008	359	21	0
12345678	2014/03/12-14-23-28	0	27.36	0	123459	0,000007	359	21	0

**Serial Number**: is the serial number of the module, which allows it to be uniquely identified

Data & Time: log time information (year/month/day-hours-min-sec)

Status: STATUS register in 16-bit binary mode

bit [0] = fail global
 bit [6] = fail hw

bit [1] = alarm
 bit [7] = fail log
 bit [2] = over range
 bit [8] = fail RTC

• bit [3] = under range • bit [9] = fail EEPROM

• bit [4] = Din status • bit [10] = fail sensor

• bit [5] = Dout status

**Analog Input**: analogue input information in mA, mV,  $^{\circ}$ C or  $\Omega$  (as configured)

Totalizer: totalization of the number of pulses on the digital input. The totalization display follows the set sampling rate

Period: measurement of the period in us. If the frequency input is not connected, the value tends to infinity

Frequency: frequency from the period measurement, expressed in Hz. If the frequency input is not connected, it is set to zero

Analog Output: analogue output value in mV or uA (as configured)

**Input type**: is the type of input probe

• 0 = Voltage • 1 = Current • 2 = Potentiometer • 3 = Resistor $400\Omega$ -2Wire • 4 = Resistor $400\Omega$ -3Wire • 5 = Resistor $400\Omega$ -4Wire • 20 = PT1000-4Wire

• 6 = Resistor $4000\Omega$ -2Wire • 21 = TC J • 7 = Resistor $4000\Omega$ -3Wire • 22 = TC K

• 8 = Resistor  $4000\Omega$  - 4Wire • 23 = TCR

9 = NI100-2Wire
 10 = NI100-3Wire
 24 = TC S
 25 = TC T

• 11 = NI100-4Wire • 26 = TC B







- 12 = PT100-2Wire
- 27 = TC E
- 13 = PT100-3Wire
- 28 = TC N
- 14 = PT100-4Wire

#### Output type: is the analogue output configuration

- bit [0] = Voltage/Current
- bit [1-2] = analog input, frequency, period, totalizer
- bit [3] = fail under-range
- bit [4] = fail over-range
- bit [5] = fail HW
- bit [6] = fail log

- bit [7] = fail RTC
- bit [8] = fail EEPROM
- bit [9] = fail alarm
- bit [10-11] = 0 above threshold /1 below threshold /2 outside thresholds /3 inside thresholds
- bit [12] = Manual mode

#### **PRODUCT FEATURES**

The following functions can be configured using the configuration software or the dedicated registers:

#### **Modbus**

Address, baud rate, parities and stop bits are adjustable.

#### Inputs/output

- Analogue input type and measurement filter [Reg. 40101, 40103]
- Digital input type and sampling rate [Reg. 40102, 40105]
- Output type [Reg. 40106]
- Retransmission of the input measurement (among those available) or manual handling via Modbus RTU on the analogue output [Reg. 40106]
- Input and output scaling [Reg. 40107 40112]
- Digital output start-up status [Reg. 40113]

#### **Totalizer**

Counting edge for totaliser (limit 232) [Reg. 40007]. The totaliser memory is non-volatile (it resets on power failure).

#### **Analogue output alarm**

By configuring the register [40106] it is possible to determine whether an alarm is to be associated with the analogue output (in addition to the value already present on the output itself).

**PLEASE NOTE**: in the event of an alarm, the output is set to 21mA or 10.5V depending on the analogue output mode setting (current or voltage) selected via the configuration software.

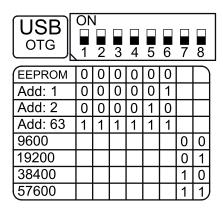
#### **Digital output alarm**

By configuring the register [40113] it is possible to define which alarms are to be associated (and possibly the threshold [reg. 40114 - 40116] and hysteresis [reg. 40118] of the variable that triggers the alarm) and whether the alarm is active low/high [reg. 40113].

#### **DEVICE CONFIGURATION**

#### Dip-switch Modbus RTU address and baud rate setting

The DIP switches on the front of the module can be used to change the Modbus RTU address and baud rate. If all DIP switches are set to zero, the module takes the configuration from the EEPROM, otherwise it takes the configuration set by the DIP switches.



Addresses greater than 63 and baud rates other than those selected by the DIP switches can be configured using the Q-WIZARD configuration tool or the Modbus RTU functions below by acting on the dedicated registers.

Raising DIP switch 1, visible through the hole in the product casing (see figure below), activates the dynamic termination ( $120\Omega$ ) of the Modbus RTU (to be performed only on the last module in the chain - see Figure 2 under RS485 bus termination).

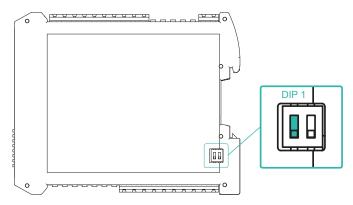


Figure 3: Dip-switch

**PLEASE NOTE:** To activate any DIP switch changes, it is necessary to switch the unit off and on again.

#### **Functionality configuration**

It is possible to connect to the product via an RS485 serial device, such as our Q-USB485, or via the microUSB port.

If the microUSB is used for configuration only, the main power supply from the terminals is not necessary, but it must be present to have all the functions active (real-time monitoring); if configuration is made from the terminals, the power supply must always be present.

The configuration of the module can be done with our **Q-WIZARD configuration tool** or with any third-party Modbus master, by acting on the registers - see page 15.

#### **Q-WIZARD**

Using the Q-WIZARD configuration tool (downloadable from here), all device parameters can be configured by following the simple, intuitive steps. In addition to the configuration of various parameters, inputs and outputs, the Q-WIZARD also allows real-time monitoring of device variables.



#### **Third-party Modbus Master**

Alternatively, the product can communicate directly with a third-party Modbus RTU Master using the communication settings according to the DIP switch configuration (when using microUSB the DIP switch settings are irrelevant).

The communication protocol supported is Modbus RTU Slave:

- Modbus RTU connections: A+ and B- according to Modbus RTU standards
- Supported Modbus RTU functions: 03 hexadecimal (read multiple registers, max 100), 06 hexadecimal (write single), 10 hexadecimal (write multiple registers)
- Modbus RTU address numbering is by convention '1 BASED' (standard), but the physical register is base 0; the logical address, e.g. 40010, corresponds to the physical address #9, as required by Modbus RTU standards

**PLEASE NOTE:** All setting changes of calibration and configuration parameters must be followed by the flash save command 0xC1C0 = Flash settings save command in register 42001; changes of device communication parameters in addition must also be followed by the command 0xC1A0 = Reboot command in register 42001.

In this case, all device configurations are performed by accessing the Modbus RTU register map available in the last chapter of this document using the functions:

- Read holding registers (function 03 hexadecimal)
- Write single holding register (function 06 hexadecimal)
- Write multiple registers (function 10 hexadecimal)

#### Function 03 Hexadecimal (Read Holding Registers)

This function is used to read the contents of a contiguous block of holding registers (words). The request frame specifies the source register address and the number of registers to read. A maximum of 120 registers (words) can be read with a single request, unless otherwise specified. The register data in the response message is packaged as two bytes per register (word), with the binary contents right-justified within each byte. For each register, the first byte contains the most significant bits (MSB) and the second byte contains the least significant bits (LSB).

Request Frame			
Description	Lenght	Value	Comments
Physical address	1 byte	1 to F7 HEX (1 to 247)	
Function code	1 byte	03 HEX	
Starting address	2 bytes	0000 to FFFF HEX	Bytes order: MSB, LSB
Number of registers (N word)	2 bytes	1 to 10 HEX (1 to 16)	Bytes order: MSB, LSB
CRC	2 bytes		

Response frame (right action)				
Description	Lenght	Value	Comments	
Physical address	1 byte	1 to F7 HEX (1 to 247)		
Function code	1 byte	03 HEX		
Required Number of bytes	1 byte	N word * 2		
Register value	N*2 bytes		Bytes order: MSB, LSB	
CRC	2 bytes			

Response frame (wrong action)					
Description	Lenght	Value	Comments		
Physical address	1 byte	1 to F7 HEX (1 to 247)	Possible exception:		
Function code	1 byte	83 HEX	01: illegal function		
Exception code	1 byte	01, 02, 03, 04 (see note)	02: illegal data address		
CRC	2 bytes		03: Illegal data value		
	•		04: Slave device failure		



### Function 06 Hexadecimal (Write Single Holding Register)

This function is used to write a single holding register. The request frame specifies the address of the register (word) to be written and its contents. The correct response is an echo of the request, returned after the contents of the register have been written.

Request frame			
Description	Lenght	Value	Comments
Physical address	1 byte	1 to F7 HEX (1 to 247)	
Function code	1 byte	06 HEX	
Starting address	2 bytes	0000h to FFFF HEX	Bytes order: MSB, LSB
Register value	2 bytes	0000h to FFFF HEX	Bytes order: MSB, LSB
CRC	2 bytes		

Response frame (right action)					
Description	Lenght	Value	Comments		
Physical address	1 byte	1 to F7 HEX (1 to 247)			
Function code	1 byte	06 HEX			
Starting address	2 bytes	0000h to FFFF HEX	Bytes order: MSB, LSB		
Register value	2 bytes	0000h to FFFF HEX	Bytes order: MSB, LSB		
CRC	2 bytes				

Response frame (wrong action)						
Description	Lenght	Value	Comments			
Physical address	1 byte	1 to F7 HEX (1 to 247)	Possible exception:			
Function code	1 byte	86 HEX	01: illegal function			
Exception code	1 byte	01, 02, 03, 04 (see note)	02: illegal data address			
CRC	2 bytes		03: Illegal data value			
	·		04: Slave device failure			

### Function 10 Hexadecimal (Write Multiple Registers)

This function is used to write a block of contiguous registers (maximum of 2). The required values to be written are specified in the data field of the request. The data is packed as two bytes per register.

A correct response returns the function code, the starting address and the number of registers written.

Request frame					
Description	Lenght	Value	Comments		
Physical address	1 byte	1 to F7 HEX (1 to 247)			
Function code	1 byte	10 HEX			
Starting address	2 bytes	0000 to FFFF HEX	Bytes order: MSB, LSB		
Number of registers (N word)	2 bytes	0001 to 0078 HEX	Bytes order: MSB, LSB		
Byte counting	1 byte	N word * 2			
Register value	N * 2 bytes	value	Bytes order: MSB, LSB		
CRC	2 bytes				







Response frame (right action)					
Description	Lenght	Value	Comments		
Physical address	1 byte	1 to F7 HEX (1 to 247)			
Function code	1 byte	10 HEX			
Starting address	2 bytes	0000 to FFFF HEX	Bytes order: MSB, LSB		
Number of registers (N word)	2 bytes	0001 to 0078 HEX	Bytes order: MSB, LSB		
CRC	2 bytes				

Response frame (wrong action)						
Description	Lenght	Value	Comments			
Physical address	1 byte	1 to F7 HEX (1 to 247)	Possible exception:			
Function code	1 byte	90 HEX	01: illegal function			
Exception code	1 byte	01, 02, 03, 04 (see note)	02: illegal data address			
CRC	2 bytes		03: Illegal data value			
	,		04: Slave device failure			

#### **FIRMWARE UPDATE**

Using a standard pendrive to hold the file and a micro-USB OTG cable, the product is ready for firmware updates via the USB port.

To update the firmware, simply remove power from the module, insert the pendrive on the card with the file on it and restore the power supply. At this point the card will automatically download the file and update the firmware without changing the settings during programming.

The FAIL LED will flash during the update phase.



### **REGISTER MAP**

Register Name	Description	Register Type	R/W	Default	Range	Address Modbus
Machine ID	Machine ID	UShort [16b]	R	5	Kange	40001
FW version	Firmware version	UShort [16b]	R	0		40002
SN	Serial number	UShort [16b]	R	Ū		40003
Status	bit 0 → fail global bit 1 → alarm bit 2 → over-range bit 3 → under-range bit 4 → Din status bit 5 → Dout status bit 6 → fail HW bit 7 → fail log bit 8 → fail RTC bit 9 → fail EEPROM bit 10 → fail sensor	UShort [16b]	R			40005
Input Value	Input Value normalized	UShort [16b]	R/W		010000	40006
Totalizer	Totalizer	ULong [32b]	R/W		0232-1	40007
Output Value	Output Value [mV or uA]	UShort [16b]	R/W		065535	40009
Input Value	Input Value	Float [32b-MSW]	R			40010
Period	Period [us]	Float [32b-MSW]	R			40012
Frequency	Frequency [Hz]	Float [32b-MSW]	R			40014
Cold Junction Temp	Cold Junction Temperature	Float [32b-MSW]	R			40016
TC read	TC uV readed	Float [32b-MSW]	R			40018
Digital output	bit[0] = disabled/enabled	UShort [16b]	R			40020
DIP-switch status	bit [0-7]=dip switch status bit [0] = dip switch position 8 bit [1] = dip switch position 7 Bit [7] = dip switch position 1	UShort [16b]	R			40021
Third wire resistance	Third wire resistance [Ohm]	Float [32b-MSW]	R			40022
Duty-cycle	Duty-cycle of digital input	Float [32b-MSW]	R			40024
Analog input type	0=Voltage, 1=Current, 2=Potentiometer, 3=Resistor400-2W, 4=Resistor400-3W, 5=Resistor4000-2W, 7=Resistor4000-3W, 8=Resistor4000-3W, 9=N1100-2W, 10=N1100-3W, 11=N1100-4W, 12=PT100-2W, 13=PT100-3W, 14=PT100-4W, 15=PT500-2W, 16=PT500-3W, 17=PT500-4W, 18=PT1000-2W, 19=PT1000-4W, 21=TC J, 22=TC K, 23=TC R, 24=TC S, 25=TC T, 26=TC B, 27=TC E,	UShort [16b]	R/W	0	028	40101
Digital input type	28=TC N  0 → Reed  1 → npn 2 fili 2 → npn 24 V (3 fili) 3 → pnp 24 V (3 fili) 4 → NAMUR 5 → Fotoelettrico 6 → Hall 7 → Ingresso 24 V 8 → TTL 9 → Riluttanza variabile	UShort [16b]	R/W	0		40102





Register Name	Description	Register Type	R/W	Default	Range	Address Modbus
Temperature mode	bit[0] = unit measure °C/°F bit[7-15] analog filter value (0-32)	UShort [16b]	R/W	1	132	40103
Totalizer mode	bit[1] → <b>rising</b> /falling edge	UShort [16b]	R/W	0		40104
Digital Input filter	Value: 0=disabled, n sample average	UShort [16b]	R/W		065535	40105
Output analog mode	bit[0] = 0 → Voltage 1 → Current bit[1-2] = 0 → analog input 1 → frequency input 2 → period input 3 → totalizer input 4 → duty-cycle bit[3] = fail under-range bit[4] = fail over-range bit[5] = fail HW bit[6] = fail log bit[7] = fail RTC bit[8] = fail alern bit[10-11] = 0 → greater than a threshold 1 → lower than a threshold 2 → outside two thresholds 3 → inside two thresholds bit[12] = Manual mode"	UShort [16b]	R/W	0		40106
Output analog input begin scale	Output analog input begin scale	Float [32b-MSW]	R/W	0.0		40107
Output analog input end scale	Output analog input end scale	Float [32b-MSW]	R/W	10000.0		40109
Output analog begin scale	Output analog begin scale	UShort [16b]	R/W	0	065535	40111
Output analog end scale	Output analog end scale	UShort [16b]	R/W	10000	065535	40112
Digital output settings	bit[0] = Power-Up Value bit[1] = Fail under-range bit[2] = Fail over-range bit[3] = Fail HW bit[4] = Fail log bit[5] = Fail RTC bit[6] = Fail EEPROM bit[7] = Fail alarm bit[8] = Fail Din bit[9] = Din/Din inverted bit[10] = Alarm / Fail digital output state: 0 → Low 1 → High	UShort [16b]	R/W	0		40113
Alarm Low Trip	Low Trip alarm value	Float [32b-MSW]	R/W	0.0		40114
Alarm High Trip	High Trip alarm value	Float [32b-MSW]	R/W	0.0		40116
Alarm Hysteresis	Hysteresis alarm value	Float [32b-MSW]	R/W	0.0		40118
Address, parity, stopbits	MSB: modbus address LSB: bit[0-1] = parity	UShort [16b]	R/W	256		40120
Baudrate	0 → 1200 1 → 2400 2 → 4800 <b>3 → 9600</b> 4 → 19200 5 → 38400 6 → 57600 7 → 115200	UShort [16b]	R/W	3	07	40121
Log mode	bit[0] = disabled/enabled	UShort [16b]	R/W	0		40122
Log sample	Log sample time [s]	UShort [16b]	R/W	1	065535	40123
Log name	Log name (15caratteri MAX)	UShort [16b]	R/W	0		40124
	Log name (15caratteri MAX)	UShort [16b]	R/W	0		40125
Log name	,					
Log name	Log name (15caratteri MAX)	UShort [16b]	R/W	0		40126
Log name	Log name (15caratteri MAX)	UShort [16b]	R/W	0		40127
Log name	Log name (15caratteri MAX)	UShort [16b]	R/W	0		40128
Log name	Log name (15caratteri MAX)	UShort [16b]	R/W	0		40129
		rugh r Frank 3	Dhai			
Log name	Log name (15caratteri MAX)	UShort [16b]	R/W	0		40130
	Log name (15caratteri MAX) Log name (15caratteri MAX)	UShort [16b] UShort [16b]	R/W R/W	0		40130 40131





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Register Name	Description	Register Type	R/W	Default	Range	Address Modbus
RTC month	RTC: month (1-12)	UShort [16b]	R/W		112	41002
RTC day month	RTC: day month (1-31)	UShort [16b]	R/W		131	41003
RTC hour	RTC: hour (0-23)	UShort [16b]	R/W		123	41004
RTC minute	RTC: minute (0-59)	UShort [16b]	R/W		059	41005
RTC second	RTC: second (0-59)	UShort [16b]	R/W		059	41006
Command	1=Reboot 2=Flash settings save 3=Set factory configuration 4=Reset Totalizer 5=Load Totalizer	UShort [16b]				42001

#### **LEGEND:**

Short [16b] = Signed Short (16 bit) UShort [16b] = Unsigned Short (16 bit)

Long [32b-MSW] = Signed Long (32 bit - MSW First Register) Long [32b-LWS] = Signed Long (32 bit - LSW First Register) ULong [32b-LSW] = Unsigned Long (32 bit - LSW First Register) ULong [32b] = Unsigned Long (32 bit)

Float [32b-MSW] = Float (32 bit - MSW First Register) Float [32b-LSW] = Float (32 bit - LSW First Register)

UInt [16b] = Unsigned Integer (16 bit)
UInt [32b-MSW] = Unsigned Integer (32 bit - MSW First Register)
Int [64b-LSW] = Signed Long Long (64 bit - LSW First Register)