# QA-VI



QA-VI
Power
Fail
Rx
Tx
Dout

USB
OTG

))).E.M.
ELECTRONIC PERFORMANCE

QE3D
QUALITY ELECTRONIC DESIGN

QWizard

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## for news, updates and downloads

# CONTENTS

PAGE
**2** of **16**

QA-VI
PRODUCT MANUAL

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## SAFETY WARNINGS AND CAUTIONS

The following warnings and cautions must be observed to ensure personal safety and prevent damage.

**Death** or **serious injury** may result from failure to heed this warning.

**Material damage** or **serious personal injury** may result from failure to heed this warning.

The manufacturer **declines all responsibility** for electrical safety in the event of improper use of the equipment.

It is essential to read the entire contents of this manual before carrying out any work.

Installation and commissioning must be carried out by qualified personnel only.

Before commissioning, make sure that:

- the maximum values for all connections are not exceeded; refer to the product data sheet;
- the connection cables are not damaged or live during wiring;
- the direction of current flow and phase rotation are correct.

During installation, ensure that a switch or circuit-breaker is near the product and easily accessible.

The unit must be uninstalled if safe operation can no longer be guaranteed (e.g. visible damage). Disconnect all connections in this case. The unit should be returned to the manufacturer or to an authorised service centre for repair.

**WARNING:** High-intensity magnetic fields may alter the values measured by the transformer. Avoid installation near: permanent magnets, electromagnets, or iron masses. If irregularities are detected, reposition or move the unit to a more suitable location.

Failure to observe the warnings may result in damage to the equipment or failure to operate as intended.

Please note that the information on the nameplate must be observed.

It is necessary to comply with national regulations when installing and picking materials for power lines.

Repairs and modifications must be carried out only by the manufacturer. It is forbidden to open the case and make any changes to the device. Tampering with the device will invalidate the warranty.

The product described in this document may only be used for the specified application. The maximum performance data and environmental conditions specified in the product data sheet must be observed. Proper transport and storage, as well as professional assembly, installation, handling and maintenance are required for the correct and safe operation of the device.

Use under ambient conditions other than those specified, application of signals or voltages other than those specified, may cause significant deviations from the specified measurement tolerances, which may be irreversible.

Although the contents of this document have been checked for accuracy, it may contain errors or inconsistencies and we cannot guarantee its completeness or accuracy.

This document is subject to periodic revision and updating. QEED reserves the right to make changes to the product and/or its technical documentation at any time in the interests of continuous quality improvement. Always consult the latest version of the documentation available on the website:

**www.qeed.it**

If you find any errors or missing information in this document, please notify us by e-mail to:

**technical@qeed.it**

Disposal of waste electrical and electronic equipment (applicable in the European Union and other countries with separate collection). The symbol on the product or its packaging indicates that the product should not be treated as household waste. Instead, it will be handed over to an authorised collection point for the recycling of electrical and electronic waste. Ensuring that the product is disposed of properly will prevent potential negative effects on the environment and human health, which could otherwise be caused by inappropriate waste management of the product. Recycling materials helps to conserve natural resources. For further information, please contact your local authority, waste disposal service or the retailer from whom you purchased the product.

## PRODUCT OVERVIEW

The QA-VI is a USB and RS485 configurable voltage/current converter. It can read analogue current and voltage inputs. It has a software configurable 0...20mA or 0...10V output and an alarm contact.

It can run from both AC or DC power.

It has full galvanic isolation between power supply, serial and USB interface and inputs and outputs.

Power/error/communication/output status LEDs are on the front of the case.

RS485 serial interface for communication with Modbus RTU protocol, either from the **Q-WIZARD configuration tool (download at link)** or with third party Modbus masters by acting on register map registers.

Data acquisition via USB with integrated real-time clock data storage, with cable or OTG pendrive only.

Ready for DIN rail mounting with T-BUS (optional) for fast connection with hot insertion/removal option.



**1**  Status LEDs
**2**  MicroUSB Port
**3**  Settings DIP switch
**4**  Power supply terminals
**5**  Input terminals
**6**  Output terminals
**7**  T-BUS terminal for both power supply and Modbus RTU communication (optional)

PAGE
**4** of **16**

QA-VI
PRODUCT MANUAL

QEED
QUALITY ELECTRONIC DESIGN
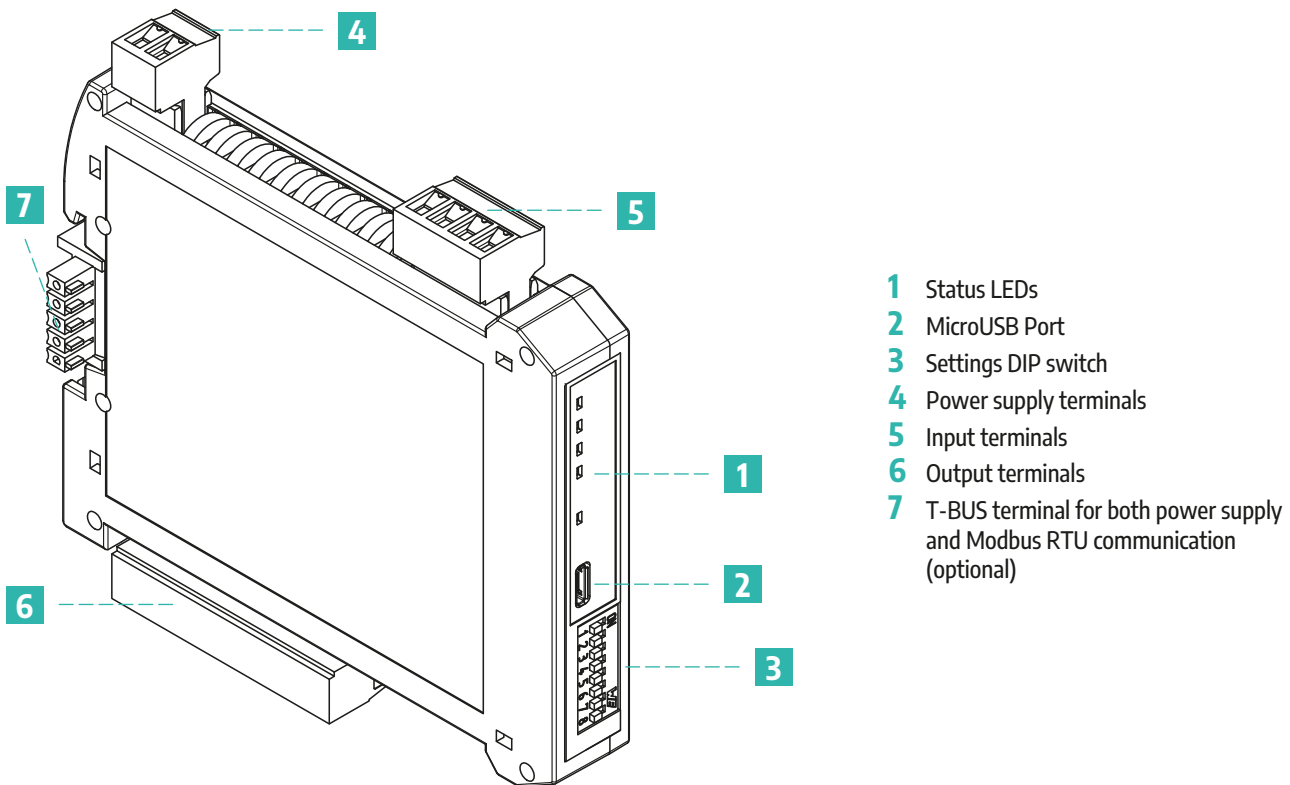
## Inputs

- Voltage: configurable* 0-10V, 100kΩ input impedance, 1mV resolution
- Current: configurable* up to 20mA, 20Ω input impedance, 2μA MAX resolution

## Outputs

- Voltage: configurable* 0-10V, minimum load resistance 2kΩ
- Current: configurable* 0...20mA, maximum load resistance 600Ω
- Alarm contact: 5A / 230VAC relay, configurable via Q-WIZARD software

## Communication interface

- RS485 Modbus RTU: connection to RS485 serial bus on module base via adapter (T-BUS optional) or terminals. Front dip-switch for manual setting of address and baud rate
- USB for configuration

* Using the configuration software, it is possible to scale the inputs and outputs as required, selecting the input measurement interval (BEGIN SCALE INPUT and END SCALE INPUT parameters in the configuration software) to which the analogue output signal is assigned (BEGIN SCALE OUTPUT and END SCALE OUTPUT parameters in the configuration software).

If manual control via Modbus RTU is selected from the interface, it is possible to manage the module as if it were an AO (Analogue Output) or a DO (Digital Output), thus freeing the analogue and digital output from the selected input. The analogue output is managed via the RS485 Modbus RTU (see register map).

## Reports and alarms

The device notifies the user of the following faults via the LED interface:

- Input signal below threshold
- Input signal above threshold
- HW error in the measurement chain
- LOG problem of the real time clock storing the date and time
- RTC problem during data acquisition (no memory on USB stick, USB stick not recognised)
- EEPROM problem on the configuration microprocessor (module out of order, configuration lost)

These anomalies can also be associated with the analogue and/or digital output (even simultaneously) in the form of alarms.

An additional alarm can also be associated with the analogue and/or digital output on the input measurement reported at the output; depending on the configuration software settings, this alarm can be triggered when the measurement is above/below a set threshold or between/beyond 2 set thresholds.

**PLEASE NOTE**: in the event of an alarm, the output is set to 21mA or 10.5V depending on the analogue output mode setting (current or voltage) selected via the configuration software.

## Data logging

It is possible to activate the LOG function for data acquisition on a USB flash drive from the configuration software's dedicated menu.

The extension of the log file can be of the following types: .xls, .xlsx, .csv, .txt, .dat, .log and can be changed by simply changing the extension to the file name in the configuration tool's save box. The default extension is text.

The minimum sampling time is 1 second and the maximum is approximately 18 hours.
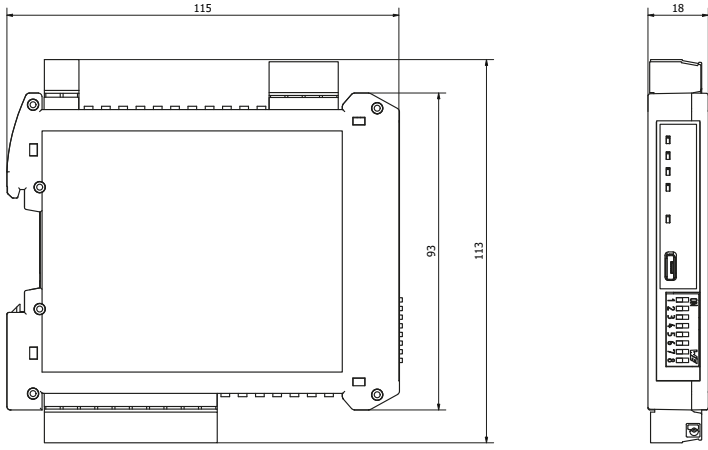
# TECHNICAL SPECIFICATIONS

## Electrical characteristics

| | |
|---|---|
| Power supply | 10÷40 V$_{DC}$ or 20÷28 V$_{AC}$ @50/60Hz |
| Current consumption | 250mA max |
| Isolation | 1.5kV galvanic isolation between inputs, analogue outputs, RS485 and USB interfaces and power supply |
| Precision class | 0,1% F.S. |
| Temperature coefficient | <100ppm/°C |
| Retransmitted output | Analogue configurable in passive and active current (max voltage 24V) |
| | Supply for passive sensors: 13V$_{DC}$, 30mA max |
| Resolution | 16 bit |
| Analog input* | • Voltage: configurable* 0-10V, 100kΩ input impedance, 1mV resolution |
| | • Current: configurable* up to 20mA, 20Ω input impedance, 2µA MAX resolution |
| * Sampling time | 100ms, with configurable averaged input value up to a maximum of 32 samples |
| Output | Analog configurable in: |
| | • Voltage: configurable* 0-10V, minimum load resistance 2k |
| | • Current: configurable* 0...20mA, maximum load resistance 600Ω |
| | Digital (relay SPDT 250V$_{AC}$, 5A MAX) |
| Communication interface | RS485 Modbus RTU |
| | microUSB port |
| Visual interface | Status LEDs |

## Communication characteristics

| | |
|---|---|
| Protocol | Modbus RTU |
| Baudrate | 1200÷115200 bps (default 9600) |
| Addresses | 1÷247 (default 1) |
| Data format | 1 start bit, 8-bit data, NO/ODD/EVEN parity (default NO parity) |
| Response delay | 1÷1000ms |
| Connection | Via removable terminal, T-BUS or microUSB |
| Visual interface | Status LEDs |

PAGE
**6** of **16**

QA-VI
PRODUCT MANUAL

QE3D
QUALITY ELECTRONIC DESIGN

## General data

| | |
|---|---|
| Working temperature | -15÷60° C |
| Storage temperature | -40÷85° C |
| Relative humidity | 10÷90% not condensing |
| Elevation | Up to 2000m a.s.l. |
| Protection degree | IP20 |
| Measurements | 115x113x18 mm |
| | |
| Weight | 116 g |
| Terminal cable cross-section | 0.05÷1.5 mm² (30÷14 AWG) |
| Approvals and certifications | EN 61000-6-3 + A1 2011; EN64000-6-2/2005; EN61010-1/2010 — CE UK CA |
| Installation | DIN rail mounting |

## Order codes

| | |
|---|---|
| Product | QA-VI |
| Product without logo | QA-VI-T-NL |
| T-BUS | QA-TBUS-22 |

## CONNECTION AND INSTALLATION

For the connection of several instruments with reduced wiring, the unit is designed for DIN rail mounting, with or without T-BUS connector.

The functionality of the terminals is described below:

| | |
|---|---|
| 16 AC<br>17 AC<br>MAX 2,5 VA 10-40 Vdc 20-28 Vac | Device power supply.<br>**Please note:** Wiring must be protected against short circuits and/or accidental faults |
| 1<br>2<br>3<br>4 | Analogue input connection:<br>- Active current input: terminals 2 (positive) and 3<br>- Passive current input: terminals 2 (positive) and 4<br>- Voltage input: terminals 1 (positive) and 3 |
| MAX 24V<br>OUT<br>29<br>30<br>31 | Analog output connection:<br>- Voltage: terminals 31 and 29 (positive)<br>- Active current: terminals 29 (positive) and 30<br>- Passive current: terminals 30 (positive) and 31<br>Sensor power supply from analogue output: 24V$_{DC}$, 30mA maximum |
| RELAY<br>MAX 250Vac<br>MAX 5A<br>NO 25<br>COM 26<br>NC 27 | Digital output SPDT 5A / 250V$_{AC}$ changeover relay<br>25 normally open (NO)<br>27 normally closed (NC)<br>The default setting is NO.<br>Relay 250V$_{AC}$ MAX and 5A MAX |
| ModBus RTU<br>GND 32<br>B- 33<br>A+ 34 | RS485 Modbus RTU connection: terminals 32 (GND), 33 (B-), 34 (A+) |
| AC AC GND B- A+ | T-BUS connection (requires optional T-BUS accessory):<br>the T-BUS accessory can be fitted to the module base to provide both power supply and serial communication (see figure below). The number of modules supported by the bus depends on the power supply used (please check the power consumption of the modules) |

PAGE
**8** of **16**

QA-VI
PRODUCT MANUAL

QE∃D
QUALITY ELECTRONIC DESIGN
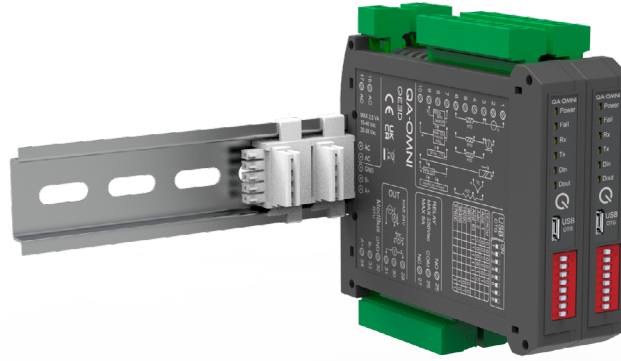
**Figure 1:** DIN-rail installation with T-BUS

## RS485 bus termination

To avoid unbalances on the transmission bus, it is advisable to insert a termination resistor at the beginning of the RS-485 bus (typically on the USB-RS485 adapter) and at the end (typically on the last slave - which can also be activated by dip-switch). It is advisable to use 120Ω resistors with 1% tolerance, which corresponds to the typical impedance of RS485 cables.

The following images are for illustrative purposes only:
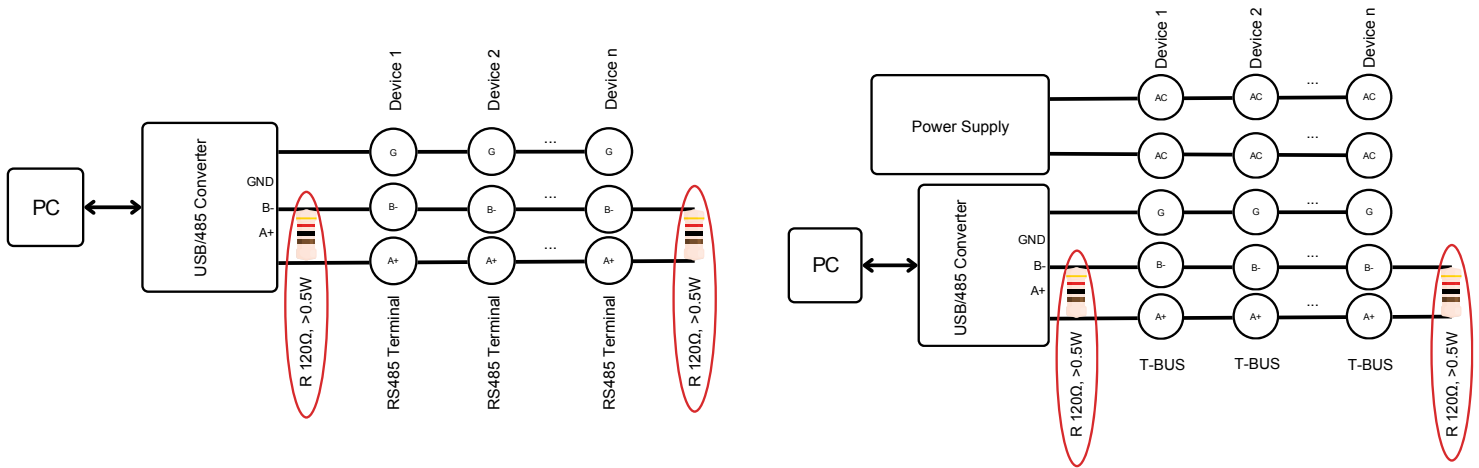


**Figure 2:** RS485 dynamic bus termination

## STATUS LEDS

| Function | Status | Meaning |
|---|---|---|
| Power (green) | ON | Powered device |
| Fail (yellow) | ON | Presence of one or more module anomalies/errors (configurable via **Q-WIZARD** or via dedicated registers- see page 15) |
| RX (red) | Flashing | The system is receiving data on the RS485 |
| TX (red) | Flashing | The system is transmitting data from RS485 |
| Dout (green) | ON | Active digital output |

## DATA LOGGING: DATA ACQUISITION

The QA-VI is able to provide a series of information regarding the module operation, alarm status, input type, output type, measured data reading, totalisation, period and frequency measurement and module output value on a local USB PENDRIVE type memory (USB KEY) connected to the module via the microUSB port. The module is equipped with an RTC Real Time Clock powered by a backup battery, allowing the recording of data with year-month-day-hour-min-sec.

Log file example of 0...10 V voltage signal, 1 sample per minute, 4-20 mA output

| Serial | Data (yyyy-mm-dd) & Time | Status | Analog Input | Analog Output | Input type | Output type |
|---|---|---|---|---|---|---|
| 12345678 | 2014/03/12-14-23-25 | 0 | 5 | 12000 | 0 | 1 |
| 12345678 | 2014/03/12-14-24-25 | 0 | 6 | 13600 | 0 | 1 |
| 12345678 | 2014/03/12-14-25-25 | 0 | 6 | 13600 | 0 | 1 |
| 12345678 | 2014/03/12-14-26-25 | 0 | 7 | 15200 | 0 | 1 |

**Serial Number**: is the serial number of the module, which allows it to be uniquely identified

**Data & Time**: log time information (year/month/day-hours-min-sec)

**Status ID:** STATUS register in 16-bit binary mode

- bit [0] = fail global
- bit [1] = alarm
- bit [2] = over range
- bit [3] = under range
- bit [4] = reserved
- bit [5] = Dout status
- bit [6] = fail hw
- bit [7] = fail log
- bit [8] = fail RTC
- bit [9] = fail EEPROM
- bit [10] = fail sensor

**Analog Input**: analogue input information in mA or mV (as configured)

**Analog Output**: analogue output value in mV or uA (as configured)

**Input type**: is the type of input probe

- 0 = Voltage
- 1 = Current

**Output type**: is the analogue output configuration

- bit [0] = Voltage/Current
- bit [1-2] = analog input
- bit [3] = fail under-range
- bit [4] = fail over-range
- bit [5] = fail HW
- bit [6] = fail log
- bit [7] = fail RTC
- bit [8] = fail EEPROM
- bit [9] = fail alarm
- bit [10-11] = 0 above threshold /1 below threshold /2 outside thresholds /3 inside thresholds
- bit [12] = Manual mode.

PAGE
**10** of **16**

QA-VI
PRODUCT MANUAL

QEED
QUALITY ELECTRONIC DESIGN

## PRODUCT FEATURES

The following functions can be configured using the configuration software or the dedicated registers:

### Modbus

Address, baud rate, parities and stop bits are adjustable

### Inputs/output

- Analogue input type and measurement filter [Reg. 40101, 40103]
- Digital input type and sampling rate [Reg. 40102, 40105]
- Output type [Reg. 40106]
- Retransmission of the input measurement (among those available) or manual handling via Modbus RTU on the analogue output [Reg. 40106]
- Input and output scaling [Reg. 40107 - 40112]
- Digital output start-up status [Reg. 40113]

### Analogue output alarm

By configuring the register [40106] it is possible to determine whether an alarm is to be associated with the analogue output (in addition to the value already present on the output itself).

**PLEASE NOTE**: in the event of an alarm, the output is set to 21mA or 10.5V depending on the analogue output mode setting (current or voltage) selected via the configuration software.

### Digital output alarm

By configuring the register [40113] it is possible to define which alarms are to be associated (and possibly the threshold [reg. 40114 - 40116] and hysteresis [reg. 40118] of the variable that triggers the alarm) and whether the alarm is active low/high [reg. 40113].

## DEVICE CONFIGURATION

### Dip-switch Modbus RTU address and baud rate setting

The DIP switches on the front of the module can be used to change the Modbus RTU address and baud rate. If all DIP switches are set to zero, the module takes the configuration from the EEPROM, otherwise it takes the configuration set by the DIP switches.

| USB OTG | ON 1 2 3 4 5 6 7 8 | | | | | | | |
|---------|---|---|---|---|---|---|---|---|
| EEPROM | 0 | 0 | 0 | 0 | 0 | 0 | | |
| Add: 1 | 0 | 0 | 0 | 0 | 0 | 1 | | |
| Add: 2 | 0 | 0 | 0 | 0 | 1 | 0 | | |
| Add: 63 | 1 | 1 | 1 | 1 | 1 | 1 | | |
| 9600 | | | | | | | 0 | 0 |
| 19200 | | | | | | | 0 | 1 |
| 38400 | | | | | | | 1 | 0 |
| 57600 | | | | | | | 1 | 1 |

Addresses greater than 63 and baud rates other than those selected by the DIP switches can be configured using the **Q-WIZARD configuration tool** or the Modbus RTU functions below by acting on the dedicated registers.

Raising DIP switch 1, visible through the hole in the product casing (see figure below), activates the dynamic termination (120Ω) of the Modbus RTU (to be performed only on the last module in the chain - see Figure 2 under RS485 bus termination).
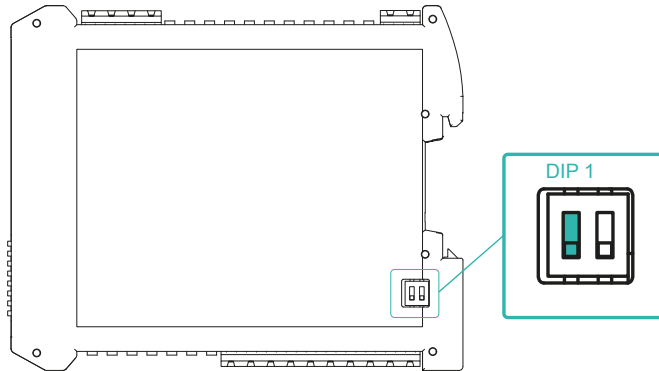


**Figure 3:** Dip-switch

**PLEASE NOTE:** To activate any DIP switch changes, it is necessary to switch the unit off and on again.

### Functionality configuration

It is possible to connect to the product via an RS485 serial device, such as our Q-USB485, or via the microUSB port.

If the microUSB is used for configuration only, the main power supply from the terminals is not necessary, but it must be present to have all the functions active (real-time monitoring); if configuration is made from the terminals, the power supply must always be present.

The configuration of the module can be done with our **Q-WIZARD configuration tool** or with any third-party Modbus master, by acting on the registers of the card - see page 15.

### Q-WIZARD

Using the **Q-WIZARD configuration tool (downloadable from here)**, all device parameters can be configured by following the simple, intuitive steps.

In addition to the configuration of various parameters, inputs and outputs, the **Q-WIZARD** also allows real-time monitoring of device variables.

## Third-party Modbus Master

Alternatively, the product can communicate directly with a third-party Modbus RTU Master using the communication settings according to the DIP switch configuration (when using microUSB the DIP switch settings are irrelevant).

The communication protocol supported is Modbus RTU Slave:

- Modbus RTU connections: A+ and B- according to Modbus RTU standards
- Supported Modbus RTU functions: 03 hexadecimal (read multiple registers, max 100), 06 hexadecimal (write single), 10 hexadecimal (write multiple registers)
- Modbus RTU address numbering is by convention '1 BASED' (standard), but the physical register is base 0; the logical address, e.g. 40010, corresponds to the physical address #9, as required by Modbus RTU standards

**PLEASE NOTE:** All setting changes of calibration and configuration parameters must be followed by the flash save command 0xC1C0 = Flash settings save command in register 42001; changes of device communication parameters in addition must also be followed by the command 0xC1A0 = Reboot command in register 42001.

In this case, all device configurations are performed by accessing the Modbus RTU register map available in the last chapter of this document using the functions:

- Read holding registers (function 03 hexadecimal)
- Write single holding register (function 06 hexadecimal)
- Write multiple registers (function 10 hexadecimal)

## Function 03 Hexadecimal (Read Holding Registers)

This function is used to read the contents of a contiguous block of holding registers (words). The request frame specifies the source register address and the number of registers to read. A maximum of 120 registers (words) can be read with a single request, unless otherwise specified. The register data in the response message is packaged as two bytes per register (word), with the binary contents right-justified within each byte. For each register, the first byte contains the most significant bits (MSB) and the second byte contains the least significant bits (LSB).

| Request Frame | | | |
|---|---|---|---|
| **Description** | **Lenght** | **Value** | **Comments** |
| Physical address | 1 byte | 1 to F7 HEX (1 to 247) | |
| Function code | 1 byte | 03 HEX | |
| Starting address | 2 bytes | 0000 to FFFF HEX | Bytes order: MSB, LSB |
| Number of registers (N word) | 2 bytes | 1 to 10 HEX (1 to 16) | Bytes order: MSB, LSB |
| CRC | 2 bytes | | |

| Response frame (right action) | | | |
|---|---|---|---|
| **Description** | **Lenght** | **Value** | **Comments** |
| Physical address | 1 byte | 1 to F7 HEX (1 to 247) | |
| Function code | 1 byte | 03 HEX | |
| Required Number of bytes | 1 byte | N word * 2 | |
| Register value | N*2 bytes | | Bytes order: MSB, LSB |
| CRC | 2 bytes | | |

| Response frame (wrong action) | | | |
|---|---|---|---|
| **Description** | **Lenght** | **Value** | **Comments** |
| Physical address | 1 byte | 1 to F7 HEX (1 to 247) | Possible exception: |
| Function code | 1 byte | 83 HEX | 01: illegal function |
| Exception code | 1 byte | 01, 02, 03, 04 (see note) | 02: illegal data address |
| CRC | 2 bytes | | 03: Illegal data value |
| | | | 04: Slave device failure |

## Function 06 Hexadecimal (Write Single Holding Register)

This function is used to write a single holding register. The request frame specifies the address of the register (word) to be written and its contents. The correct response is an echo of the request, returned after the contents of the register have been written.

| Request frame | | | |
|---|---|---|---|
| **Description** | **Lenght** | **Value** | **Comments** |
| Physical address | 1 byte | 1 to F7 HEX (1 to 247) | |
| Function code | 1 byte | 06 HEX | |
| Starting address | 2 bytes | 0000h to FFFF HEX | Bytes order: MSB, LSB |
| Register value | 2 bytes | 0000h to FFFF HEX | Bytes order: MSB, LSB |
| CRC | 2 bytes | | |

| Response frame (right action) | | | |
|---|---|---|---|
| **Description** | **Lenght** | **Value** | **Comments** |
| Physical address | 1 byte | 1 to F7 HEX (1 to 247) | |
| Function code | 1 byte | 06 HEX | |
| Starting address | 2 bytes | 0000h to FFFF HEX | Bytes order: MSB, LSB |
| Register value | 2 bytes | 0000h to FFFF HEX | Bytes order: MSB, LSB |
| CRC | 2 bytes | | |

| Response frame (wrong action) | | | |
|---|---|---|---|
| Description | Lenght | Value | Comments |
| Physical address | 1 byte | 1 to F7 HEX (1 to 247) | Possible exception: |
| Function code | 1 byte | 86 HEX | 01: illegal function |
| Exception code | 1 byte | 01, 02, 03, 04 (see note) | 02: illegal data address |
| CRC | 2 bytes | | 03: Illegal data value |
| | | | 04: Slave device failure |

## Function 10 Hexadecimal (Write Multiple Registers)

This function is used to write a block of contiguous registers (maximum of 2). The required values to be written are specified in the data field of the request. The data is packed as two bytes per register.

A correct response returns the function code, the starting address and the number of registers written.

| Request frame | | | |
|---|---|---|---|
| **Description** | **Lenght** | **Value** | **Comments** |
| Physical address | 1 byte | 1 to F7 HEX (1 to 247) | |
| Function code | 1 byte | 10 HEX | |
| Starting address | 2 bytes | 0000 to FFFF HEX | Bytes order: MSB, LSB |
| Number of registers (N word) | 2 bytes | 0001 to 0078 HEX | Bytes order: MSB, LSB |
| Byte counting | 1 byte | N word * 2 | |
| Register value | N * 2 bytes | value | Bytes order: MSB, LSB |
| CRC | 2 bytes | | |

| Response frame (right action) | | | |
|---|---|---|---|
| **Description** | **Lenght** | **Value** | **Comments** |
| Physical address | 1 byte | 1 to F7 HEX (1 to 247) | |
| Function code | 1 byte | 10 HEX | |
| Starting address | 2 bytes | 0000 to FFFF HEX | Bytes order: MSB, LSB |
| Number of registers (N word) | 2 bytes | 0001 to 0078 HEX | Bytes order: MSB, LSB |
| CRC | 2 bytes | | |

| Response frame (wrong action) | | | |
|---|---|---|---|
| **Description** | **Lenght** | **Value** | **Comments** |
| Physical address | 1 byte | 1 to F7 HEX (1 to 247) | Possible exception: |
| Function code | 1 byte | 90 HEX | 01: illegal function |
| Exception code | 1 byte | 01, 02, 03, 04 (see note) | 02: illegal data address |
| CRC | 2 bytes | | 03: Illegal data value |
| | | | 04: Slave device failure |

## FIRMWARE UPDATE

Using a standard pendrive to hold the file and a micro-USB OTG cable, the product is ready for firmware updates via the USB port.

To update the firmware, simply remove power from the module, insert the pendrive on the card with the file on it and restore the power supply. At this point the card will automatically download the file and update the firmware without changing the settings during programming.

The FAIL LED will flash during the update phase.

## REGISTER MAP

| Register Name | Description | Register Type | R/W | Default | Range | Address Modbus |
|---|---|---|---|---|---|---|
| Machine ID | Machine ID | UShort [16b] | R | 11 | | 40001 |
| FW version | Firmware version | UShort [16b] | R | 0 | | 40002 |
| SN | Serial number | UShort [16b] | R | | | 40003 |
| Status | bit  0 → fail global<br>bit  1 → alarm<br>bit  2 → over-range<br>bit  3 → under-range<br>bit  4 → reserved<br>bit  5 → Dout status<br>bit  6 → fail HW<br>bit  7 → fail log<br>bit  8 → fail RTC<br>bit  9 → fail EEPROM<br>bit 10 → fail sensor | UShort [16b] | R | | | 40005 |
| Input Value | Input Value normalized | Short [16b] | R/W | | 0...10000 | 40006 |
| Output Value | Output Value [mV or uA] | UShort [16b] | R/W | | 0...65535 | 40009 |
| Input Value | Input Value | Float [32b-MSW] | R | | | 40010 |
| Digital output | bit[0] = disabled/enabled | UShort [16b] | R | | | 40020 |
| DIP-switch status | bit [0-7]=dip switch status<br>bit [0] = dip switch position 8<br>bit [1] = dip switch position 7<br>...<br>Bit [7] = dip switch position 1 | UShort [16b] | R | | | 40021 |
| Analog Input type | Value:<br>  **0=Voltage**<br>  1=Current | UShort [16b] | R/W | | 0...28 | 40101 |
| Analog filter | bit[7-15] analog filter value (0-32) | UShort [16b] | R/W | 0 | 1...32 | 40103 |
| Output analog mode | bit[0] =<br>  **0 → Voltage**<br>  1 → Current<br>bit[1-2] = reserved<br>bit[3] = fail under-range<br>bit[4] = fail over-range<br>bit[5] = fail HW<br>bit[6] = fail log<br>bit[7] = fail RTC<br>bit[8] = fail EEPROM<br>bit[9] = fail alarm<br>bit[10-11] =<br>  **0 → greater than a threshold**<br>  1 → lower than a threshold<br>  2 → outside two thresholds<br>  3 → inside two thresholds<br>bit[12] = Manual mode | UShort [16b] | R/W | 0 | | 40106 |
| Output analog input begin scale | Output Analog Input Begin Scale | Float [32b-MSW] | R/W | 0.0 | | 40107 |
| Output analog input end scale | Output Analog Input End Scale | Float [32b-MSW] | R/W | 10000.0 | | 40109 |
| Output analog begin scale | Output Analog Begin Scale | UShort [16b] | R/W | 0 | 0...65535 | 40111 |
| Output analog end scale | Output Analog End Scale | UShort [16b] | R/W | 10000 | 0...65535 | 40112 |
| Digital Output | bit[0] = Power-Up Value<br>bit[1] = Fail under-range<br>bit[2] = Fail over-range<br>bit[3] = Fail HW<br>bit[4] = Fail log<br>bit[5] = Fail RTC<br>bit[6] = Fail EEPROM<br>bit[7] = Fail alarm<br>bit[8] = reserved<br>bit[9] = reserved<br>bit[10] = Alarm / Fail digital output state:<br>  **0 → Low**<br>  1 → High | UShort [16b] | R/W | 0 | | 40113 |

PAGE
**16** of **16**

QA-VI
PRODUCT MANUAL

QƎED
QUALITY ELECTRONIC DESIGN

| Register Name | Description | Register Type | R/W | Default | Range | Address Modbus |
|---|---|---|---|---|---|---|
| Alarm Low Trip | Alarm Low Trip value | Float [32b-MSW] | R/W | 0.0 | | 40114 |
| Alarm High Trip | Alarm High Trip value | Float [32b-MSW] | R/W | 0.0 | | 40116 |
| Alarm Hysteresis | Alarm Hysteresis value | Float [32b-MSW] | R/W | 0.0 | | 40118 |
| Address, parity, stopbits | MSB: modbus address<br>LSB: bit[0-1] = parity<br>**0 → none**<br>1 → Odd<br>2 → Even<br>LSB: bit[2] = stop bits<br>**0 → 1**<br>1 → 2 | UShort [16b] | R/W | 256 | | 40120 |
| Baudrate | 0 → 1200<br>1 → 2400<br>2 → 4800<br>**3 → 9600**<br>4 → 19200<br>5 → 38400<br>6 → 57600<br>7 → 115200 | UShort [16b] | R/W | 3 | 0...7 | 40121 |
| Log mode | bit[0] = **disabled**/enabled | UShort [16b] | R/W | 0 | | 40122 |
| Log sample | Log sample time [s] | UShort [16b] | R/W | 1 | 0...65535 | 40123 |
| Log name | Log name (15caratteri MAX) | UShort [16b] | R/W | 0 | | 40124 |
| Log name | Log name (15caratteri MAX) | UShort [16b] | R/W | 0 | | 40125 |
| Log name | Log name (15caratteri MAX) | UShort [16b] | R/W | 0 | | 40126 |
| Log name | Log name (15caratteri MAX) | UShort [16b] | R/W | 0 | | 40127 |
| Log name | Log name (15caratteri MAX) | UShort [16b] | R/W | 0 | | 40128 |
| Log name | Log name (15caratteri MAX) | UShort [16b] | R/W | 0 | | 40129 |
| Log name | Log name (15caratteri MAX) | UShort [16b] | R/W | 0 | | 40130 |
| Log name | Log name (15caratteri MAX) | UShort [16b] | R/W | 0 | | 40131 |
| RTC year | RTC : year (2000-2099) | UShort [16b] | | | 2000...2099 | 41001 |
| RTC month | RTC : month (1-12) | UShort [16b] | | | 1...12 | 41002 |
| RTC day month | RTC : day month (1-31) | UShort [16b] | | | 1...31 | 41003 |
| RTC hour | RTC : hour (0-23) | UShort [16b] | | | 1...23 | 41004 |
| RTC minute | RTC : minute (0-59) | UShort [16b] | | | 0...59 | 41005 |
| RTC second | RTC : second (0-59) | UShort [16b] | | | 0...59 | 41006 |
| Command | 1=Reboot<br>2=Flash settings save<br>3=Set factory configuration<br>4=Reset Totalizer<br>5=Load Totalizer | UShort [16b] | | | | 42001 |

**LEGEND:**

Short [16b] = Signed Short (16 bit)
UShort [16b] = Unsigned Short (16 bit)

Long [32b-MSW] = Signed Long (32 bit - MSW First Register)
Long [32b-LWS] = Signed Long (32 bit - LSW First Register)
ULong [32b-LSW] = Unsigned Long (32 bit - LSW First Register)
ULong [32b] = Unsigned Long (32 bit)

Float [32b-MSW] = Float (32 bit - MSW First Register)
Float [32b-LSW] = Float (32 bit - LSW First Register)

UInt [16b] = Unsigned Integer (16 bit)
UInt [32b-MSW] = Unsigned Integer (32 bit - MSW First Register)
Int [64b-LSW] = Signed Long Long (64 bit - LSW First Register)