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QI-50-V-485

OI-300-V-48

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SAFETY WARNINGS AND CAUTIONS

The following warnings and cautions must be observed to ensure personal safety and prevent damage.



Death or serious injury may result from failure to heed this warning.



It is necessary to comply with national regulations when installing and picking materials for power lines.



Material damage or serious personal injury may result from failure to heed this warning.



Repairs and modifications must be carried out only by the manufacturer. It is forbidden to open the case and make any changes to the device. Tampering with the device will invalidate the warranty.



The manufacturer **declines all responsibility** for electrical safety in the event of improper use of the equipment.

Installation and commissioning must be carried out by qualified



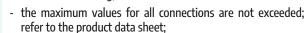
The product described in this document may only be used for the specified application. The maximum performance data and environmental conditions specified in the product data sheet



personnel only. Before commissioning, make sure that:

carrying out any work.

must be observed. Proper transport and storage, as well as professional assembly, installation, handling and maintenance are required for the correct and safe operation of the device. Use under ambient conditions other than those specified,



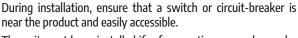
application of signals or voltages other than those specified, may cause significant deviations from the specified measurement tolerances, which may be irreversible.

- the connection cables are not damaged or live during wiring;



- the direction of current flow and phase rotation are correct.

Although the contents of this document have been checked for accuracy, it may contain errors or inconsistencies and we cannot guarantee its completeness or accuracy.





The unit must be uninstalled if safe operation can no longer be guaranteed (e.g. visible damage). Disconnect all connections in this case. The unit should be returned to the manufacturer or to an authorised service centre for repair.

This document is subject to periodic revision and updating. QEED reserves the right to make changes to the product and/ or its technical documentation at any time in the interests of continuous quality improvement. Always consult the latest version of the documentation available on the website:



www.geed.it

WARNING: High-intensity magnetic fields may alter the values measured by the transformer. Avoid installation near: permanent magnets, electromagnets, or iron masses. If irregularities are detected, reposition or move the unit to a more suitable location.

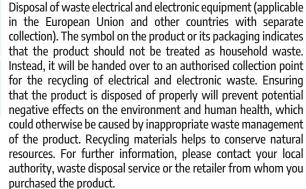
If you find any errors or missing information in this document. please notify us by e-mail to:



technical@geed.it

Failure to observe the warnings may result in damage to the equipment or failure to operate as intended.







Please note that the information on the nameplate must be observed.





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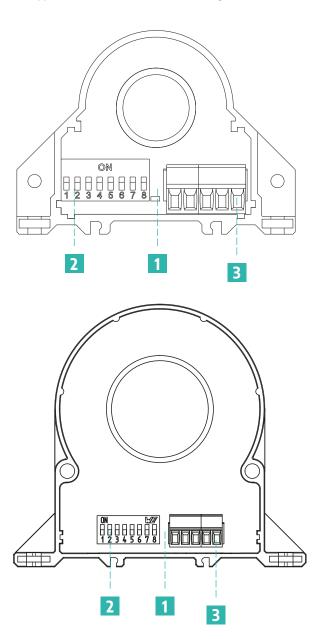
PRODUCT OVERVIEW

The QI-50-V-485 and QI-300-V-485 are 50A and 300A DC and AC current transformers that are galvanically isolated from the measurement circuit. They are similar in function and appearance to a standard active CT, but are capable of measuring both the DC and AC TRMS components.

The units are equipped with a 0-10V analogue output.

RS485 serial interface for communication with Modbus RTU protocol, either from the **Q-WIZARD configuration tool**, or with third party Modbus masters by acting on register map registers.

Mounting accessories supplied as standard for DIN rail mounting.



- 1 Status LED
 OFF: product not powered
 STEADY YELLOW: product powered
 FLASHING YELLOW: communication in progress
- 2 DIP Switch
- 3 Power supply, Vout, RS485







TECHNICAL SPECIFICATIONS

Electrical characteristics

	QI-50-V-485	QI-300-V-485		
Power supply	12÷30Vpc with reverse polarity and overter	12÷30V _{DC} with reverse polarity and overtemperature protection		
Current consumption	20mA max			
Measurable AC/DC current range	5-50A	30-300A		
0-10V analogue output range	50A RMS, ±50A DC,	300A RMS, ±300A DC,		
(values that can be set via DIP-switch)	25A RMS, ±25A DC	150A RMS, ±150A DC		
Measurement type	TRMS(AC)/DC			
Accuracy class	<0,5% F.S.	<0,5% F.S.		
@25°C, 50Hz, PF = 1				
Measurement Hysteresis	0,15% F.S.	0,2% F.S.		
Crest factor	2	1,4		
Response delay	1000ms on analog port			
	30ms on serial port			
Passband (-3dB)	DC or 20÷2000Hz	DC or 20÷2000Hz		
Isolation	3kV on bare cable for current measurement	3kV on bare cable for current measurement		
Overload	300A continuous, 2kA impulsive	300A continuous, 2kA impulsive		
Output	0÷10V	0÷10V		
Communication interface	RS485 Modbus RTU	RS485 Modbus RTU		

Communication characteristics

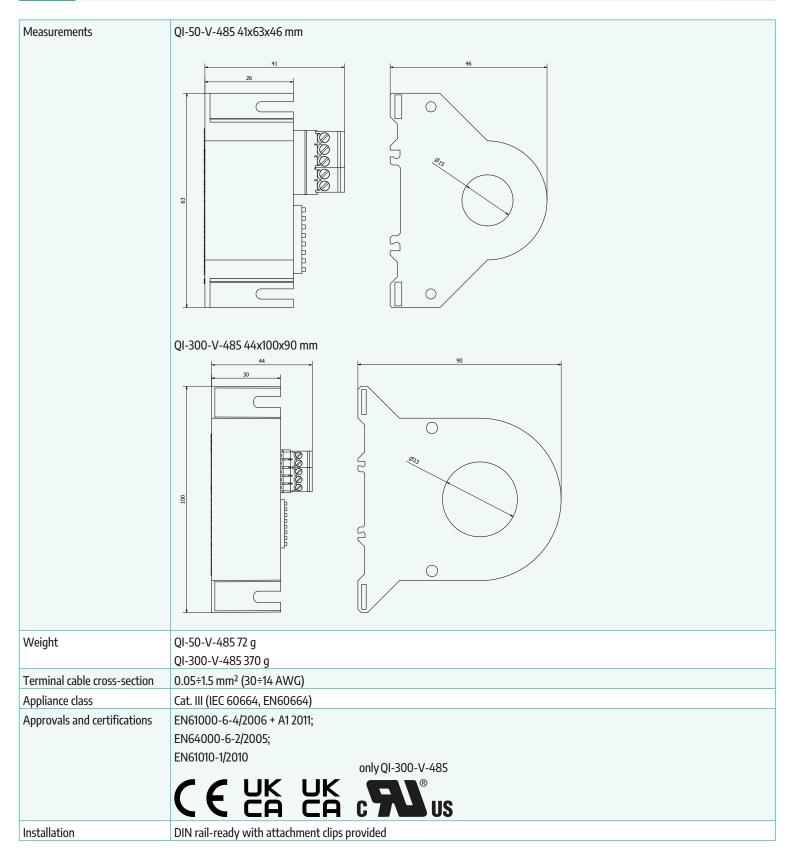
Protocol	Modbus RTU
Baudrate	1200÷115200 bps (default 9600)
Addresses	1÷247 (default 1)
Data format	1 bit di start, 8 bit dati, parità NO/ODD/EVEN (default NO parità)
Response delay	1÷1000ms
Connection	Via removable 5-pin terminal

General data

Working temperature	-15÷60° C
Storage temperature	-40÷85° C
Relative humidity	10÷90% not condensing
Elevation	Up to 2000m a.s.l.
Temperature coefficient	< 200ppm/°C
Protection degree	IP20



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Order codes

50A version	QI-50-V-485
300A version	QI-300-V-485
Attachment clips (50A version)	90000009
Attachment clips (300A version)	900000012



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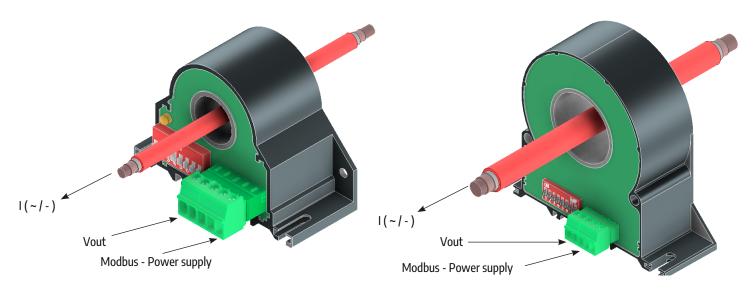




CONNECTION AND INSTALLATION

To meet different installation requirements, the unit can be mounted in four different ways (DIN rail or panel mounting, vertical or horizontal).

The system installation is as in the following image:



The conductor must be positioned as close to the product centre as possible to ensure correct current measurement.

WARNING: strong magnetic fields can alter the values measured by the instrument. Avoid installation near permanent magnets, electromagnets or ferrous masses that can significantly alter the magnetic field. In the event of anomalies, we recommend reorienting the instrument or moving it to a more suitable location.

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AVAILABLE MEASUREMENTS

Depending on the product setting, both QI-50-V-485 and QI-300-V-485 can be used for both AC and DC measurements, with the ability to vary the measurement range for greater accuracy.

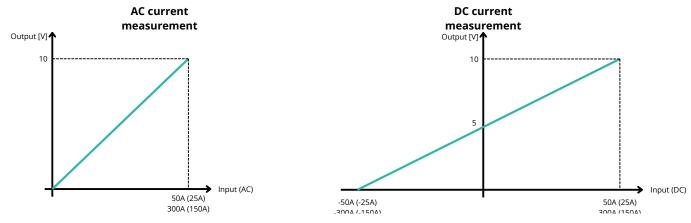


Figure 1: AC or DC measurement

Measurement and output intervals can also be set via configuration software or Modbus registers:

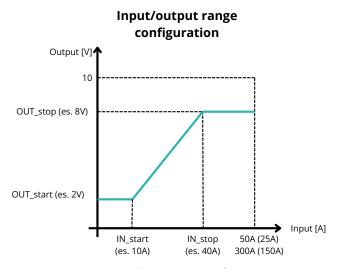


Figure 2: input/output range configuration

MEASUREMENT CONFIGURATION

By means of DIP switches 7 and 8, a different measuring range and type can be set according to the table below:

Product	Product Description DIP 7		DIP 8	
QI-300-V-485	TRMS	0		
QI-50-V-485	DC*	1		
QI-50-V-485	50A AC/DC		0	
	25A AC/DC		1	
QI-300-V-485	300A AC/DC		0	
	150A AC/DC		1	

^{*} AC measurement would give an average value equal to 0A therefore the analogue output would be fixed to 5V.

In order for the above settings to take effect, DIP switches 1-4 must not be set to 0000, which would force the use of the configuration from the EEPROM.



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PRODUCT FEATURES

Using the configuration software or acting on the dedicated registers, the following functions can be configured:

Modbus

Address, baud rate, parity and response delay can be set.

Input/Output

- Possibility of rescaling the input measuring range [Reg. 40007 40009] and the output measuring range on the 0 ÷10V output [Reg. 40011 40012]
- 2 filtering levels for moving average and current ripple reduction [Reg. 40013 40014]
- Current display threshold [Reg. 40029]
- Ampere-hour setting [Reg. 40053]

DEVICE CONFIGURATION

Baudrate setting via DIP switch

Before connecting and powering up the product, the baud rate can be set by DIP switch.

Description	DIP 1	DIP 2	DIP 3	DIP 4	DIP 5	DIP 6
Settings from EEPROM	0	0	0	0		
Address = 1	0	0	0	1		
Address = 2	0	0	1	0		
Address = 15	1	1	1	1		
Baudrate = 2400					0	0
Baudrate = 9600					0	1
Baudrate = 38400					1	0
Baudrate = 57600					1	1

Addresses greater than 15 and baud rate values other than those selectable by DIP-switch can be configured via the Q-WIZARD configuration software or with the Modbus RTU functions below by acting on the dedicated registers - see page 12.

If one of the DIP switches 1-4 is not set to zero, the default values are used to configure the input and output ranges (registers 40007 - 40012).

PLEASE NOTE: to make active all changes via DIP-switch, it is necessary to remove and restore power to the device.

Functionality configuration

Through an RS485 serial device such as our Q-USB485, it is possible to connect to the product using the Modbus RTU input terminals.

Configuration of the module can be done with our **Q-WIZARD configuration software** or with any third-party Modbus master by acting on the registers in the map - see page 12.

Q-WIZARD

Using the Q-WIZARD configuration software, it is possible to configure all device parameters by following the simple, self-explanatory steps. In addition to the configuration of various parameters, inputs and outputs, the Q-WIZARD also allows real-time monitoring of device variables.



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Third-party Modbus Master

Alternatively, the product can communicate directly with a third-party Modbus RTU Master using the communication settings according to the DIP switch configuration (when using microUSB the DIP switch settings are irrelevant).

The communication protocol supported is Modbus RTU Slave:

- Modbus RTU connections: A+ and B- according to Modbus RTU standards
- Supported Modbus RTU functions: 03 hexadecimal (read multiple registers, max 100), 06 hexadecimal (write single), 10 hexadecimal (write multiple registers)
- Modbus RTU address numbering is by convention '1 BASED' (standard), but the physical register is base 0; the logical address, e.g. 40010, corresponds to the physical address #9, as required by Modbus RTU standards

PLEASE NOTE: A maximum of 5 logs can be read in one call, more than this will result in a timeout response.

PLEASE NOTE: All setting changes of calibration and configuration parameters must be followed by the flash save command 0xC1C0 = Flash settings save command in register 40040; changes of device communication parameters in addition must also be followed by the command 0xC1A0 = Reboot command in register 40040.

In this case, all device configurations are performed by accessing the Modbus RTU register map available in the last chapter of this document using the functions:

- Read holding registers (function 03 hexadecimal)
- Write single holding register (function 06 hexadecimal)
- Write multiple registers (function 10 hexadecimal)

Function 03 Hexadecimal (Read Holding Registers)

This function is used to read the contents of a contiguous block of holding registers (words). The request frame specifies the source register address and the number of registers to read. A maximum of 120 registers (words) can be read with a single request, unless otherwise specified. The register data in the response message is packaged as two bytes per register (word), with the binary contents right-justified within each byte. For each register, the first byte contains the most significant bits (MSB) and the second byte contains the least significant bits (LSB).

Request Frame			
Description	Lenght	Value	Comments
Physical address	1 byte	1 to F7 HEX (1 to 247)	
Function code	1 byte	03 HEX	
Starting address	2 bytes	0000 to FFFF HEX	Bytes order: MSB, LSB
Number of registers (N word)	2 bytes	1 to 10 HEX (1 to 16)	Bytes order: MSB, LSB
CRC	2 bytes		

Response frame (right action)				
Description	Lenght	Value	Comments	
Physical address	1 byte	1 to F7 HEX (1 to 247)		
Function code	1 byte	03 HEX		
Required Number of bytes	1 byte	N word * 2		
Register value	N*2 bytes		Bytes order: MSB, LSB	
CRC	2 bytes			

Response frame (wrong action)					
Description	Lenght	Value	Comments		
Physical address	1 byte	1 to F7 HEX (1 to 247)	Possible exception:		
Function code	1 byte	83 HEX	01: illegal function		
Exception code	1 byte	01, 02, 03, 04 (see note)	02: illegal data address		
CRC	2 bytes		03: Illegal data value		
	•		04: Slave device failure		



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Function 06 Hexadecimal (Write Single Holding Register)

This function is used to write a single holding register. The request frame specifies the address of the register (word) to be written and its contents. The correct response is an echo of the request, returned after the contents of the register have been written.

Request frame					
Description	Lenght	Value	Comments		
Physical address	1 byte	1 to F7 HEX (1 to 247)			
Function code	1 byte	06 HEX			
Starting address	2 bytes	0000h to FFFF HEX	Bytes order: MSB, LSB		
Register value	2 bytes	0000h to FFFF HEX	Bytes order: MSB, LSB		
CRC	2 bytes				

Response frame (right action)					
Description	Lenght	Value	Comments		
Physical address	1 byte	1 to F7 HEX (1 to 247)			
Function code	1 byte	06 HEX			
Starting address	2 bytes	0000h to FFFF HEX	Bytes order: MSB, LSB		
Register value	2 bytes	0000h to FFFF HEX	Bytes order: MSB, LSB		
CRC	2 bytes				

Response frame (wrong action)			
Description	Lenght	Value	Comments
Physical address	1 byte	1 to F7 HEX (1 to 247)	Possible exception:
Function code	1 byte	86 HEX	01: illegal function
Exception code	1 byte	01, 02, 03, 04 (see note)	02: illegal data address
CRC	2 bytes		03: Illegal data value
			04: Slave device failure

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Function 10 Hexadecimal (Write Multiple Registers)

This function is used to write a block of contiguous registers (maximum of 2). The required values to be written are specified in the data field of the request. The data is packed as two bytes per register.

A correct response returns the function code, the starting address and the number of registers written.

Request frame			
Description	Lenght	Value	Comments
Physical address	1 byte	1 to F7 HEX (1 to 247)	
Function code	1 byte	10 HEX	
Starting address	2 bytes	0000 to FFFF HEX	Bytes order: MSB, LSB
Number of registers (N word)	2 bytes	0001 to 0078 HEX	Bytes order: MSB, LSB
Byte counting	1 byte	N word * 2	
Register value	N * 2 bytes	value	Bytes order: MSB, LSB
CRC	2 bytes		

Response frame (right action)					
Description	Lenght	Value	Comments		
Physical address	1 byte	1 to F7 HEX (1 to 247)			
Function code	1 byte	10 HEX			
Starting address	2 bytes	0000 to FFFF HEX	Bytes order: MSB, LSB		
Number of registers (N word)	2 bytes	0001 to 0078 HEX	Bytes order: MSB, LSB		
CRC	2 bytes				

Response frame (wrong action)					
Description	Lenght	Value	Comments		
Physical address	1 byte	1 to F7 HEX (1 to 247)	Possible exception:		
Function code	1 byte	90 HEX	01: illegal function		
Exception code	1 byte	01, 02, 03, 04 (see note)	02: illegal data address		
CRC	2 bytes		03: Illegal data value		
	,		04: Slave device failure		



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REGISTER MAP

Default values are in **bold**.

Dogistov Namo	Description	Dogistor Type	R/W	Default		Range		Address Madbus
Register Name	Description	Register Type	R/VV	QI-50-V	QI-300-V	QI-50-V	QI-300-V	Address Modbus
Machine ID	Machine ID	UShort [16b]	R	4	16			40001
FW version	Firmware version	UShort [16b]	R					40002
Address	Modbus Address	UShort [16b]	R/W			1250		40003
Delay	Answer Delay	UShort [16b]	R/W	1		1255 11000		40004
Baudrate	Baudrate: 0 = 1200 1 = 2400 2 = 4800 3 = 9600 4 = 19200 5 = 38400 6 = 57600 7 = 115200	UShort [16b]	R/W	1		07		40005
Parity	Type of parity: 0 = none 1 = ODD 2 = EVEN	UShort [16b]	R/W	0		02		40006
In_start	Start input (A)	Float [32b-LSW]	R/W	0		-50 +50	-300 +300	40007
In_stop	Stop input (A)	Float [32b-LSW]	R/W	50	300	-50 +50	-300 +300	40009
Out_start_V	Start Output (mV)	UShort [16b]	R/W	0		010000		40011
Out_stop_V	Stop Output (mV)	UShort [16b]	R/W	10000		010000		40012
Filt 1	N° of samples for mobile average (1=100 ms)	UShort [16b]	R/W	1		132		40013
Filt	Second level filter for ripple problems on AC measurement	UShort [16b]	R/W	4096		1000 20000		40014
Cut off	Cutt off value (mA)	UShort [16b]	R/W	1500				40029
RMS_A	RMS Current Value (A)	Float [32b-LSW]	R					40037
Command	OxC1CO: Flash setting save command OxD166: Dip read command OxC1AO: Reboot command	UShort [16b]	R/W					40040
Status	Status Register: bit[0] = 1: Error flash settings bit[1] = 1: Error flash calibation bit[2] = 1: Over Range bit[3] = 1: Under Range	UShort [16b]	R					40048
RMS_100	RMS Value of Current (A x 100)	Short [16b]	R					40050
RMS_sw	RMS Current Value (A) swapped	Float [32b-LSW]	R					40051
Ah	Ah counting (resettable)	Float [32b-LSW]	R/W					40053
A_MAX	Max curren tvalue/100 (resettable)	Short [16b] R/W						40055
A_min	min current value/100 (resettable)	Short [16b]	R/W					40056
Serial Number (year, Month)	Partial serial number (format: yy-MM)	UShort [16b]	R					40057
Serial Number (day, hour)	Partial serial number (format: dd-hh)	UShort [16b]	R					40058
Serial Number (min, sec)	Partial serial number (format: mm-ss)	UShort [16b]	R					40059

LEGEND:

Short [16b] = Signed Short (16 bit) UShort [16b] = Unsigned Short (16 bit)

Long [32b-MSW] = Signed Long (32 bit - MSW First Register) Long [32b-LWS] = Signed Long (32 bit - LSW First Register) ULong [32b-LSW] = Unsigned Long (32 bit - LSW First Register) ULong [32b] = Unsigned Long (32 bit)

Float [32b-MSW] = Float (32 bit - MSW First Register) Float [32b-LSW] = Float (32 bit - LSW First Register)

UInt [16b] = Unsigned Integer (16 bit)
UInt [32b-MSW] = Unsigned Integer (32 bit - MSW First Register)
Int [64b-LSW] = Signed Long Long (64 bit - LSW First Register)